# Nishant Kheterpal

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#### Education

## **University of Michigan**

9/2020 - Present

- PhD in Robotics, advised by Jean-Baptiste Jeannin
- Emphasis on formal verification for collision avoidance and machine learning systems

# **University of California, Berkeley**

8/2015 - 12/2018

- Bachelors of Science in Electrical Engineering and Computer Sciences
- Coursework in artificial intelligence, machine learning, vehicle dynamics, optimization, probability, controls, data science, computer architecture, algorithms, discrete math, linear algebra

#### **Publications**

- **N. Kheterpal**, J-B. Jeannin, "Towards a Formalization of the Active Corner Method for Collision Avoidance in PVS.", *Formal Techniques for Safety-Critical Systems*, *SPLASH*, 2022.
- **N. Kheterpal**, E. Tang, J-B. Jeannin, "Automating Geometric Proofs of Collision Avoidance with Active Corners.", Formal Methods in Computer-Aided Design, 2022. (40 accepted / 88 submissions)
- N. Kheterpal, E. Vinitsky, C. Wu, A. Kreidieh, K. Jang, K. Parvate, A. Bayen, "Flow: Open Source Reinforcement Learning for Traffic Control." *Workshop on Machine Learning Open-Source Software, NeurIPS*, 2018.
- E. Vinitsky, A. Kreidieh, L. Le Flem, **N. Kheterpal**, K. Jang, F. Wu, R. Liaw, E. Liang, A. Bayen, "Benchmarks for Reinforcement Learning in Mixed-Autonomy Traffic." *Conference on Robot Learning*. 2018.
- **N. Kheterpal**, K. Parvate, C. Wu, A. Kreidieh, E. Vinitsky, A. Bayen, "Flow: Deep Reinforcement Learning for Control in SUMO", *SUMO User Conference*, 2018.
- C. Wu, K. Parvate, **N. Kheterpal**, L. Dickstein, A. Mehta, E. Vinitsky, A. Bayen, "Framework for Control and Deep Reinforcement Learning in Traffic." *Intelligent Transportation Systems (ITSC)*, 2017 IEEE 20th International Conference on. IEEE, 2017.

## **Work Experience**

#### **Uber ATG - Research Intern**

3/2020 - 8/2020

- Developed ride comfort metrics for autonomous vehicles to improve passenger experience
- Productionized safety metrics using Traffic Conflict Technique alongside research staff
- Researcher working with Dr. Ersin Yumer and Professor Raquel Urtasun

# **Ike Robotics - Simulation Software Engineer**

1/2019 - 1/2020

- Developed simulation platform in Unreal Engine to test and validate software performance for automated trucking
- Built simulated intelligent actors and integrated control & dynamics into simulation
- Implemented distributed cloud simulation in Google Cloud Platform using Docker and Kubernetes

## **Berkeley Deep Drive - Undergraduate Researcher**

1/2017 - 12/2018

 Built Flow, an open-source framework enabling deep reinforcement learning for traffic control using vehicle simulator SUMO, RLlib, rllab, and Amazon Web Services

- Designed RL experiments in Flow to train vehicle and infrastructure agents to improve traffic flow in congested traffic scenarios
- Studied gradient accuracy, training time, and reward in deep reinforcement learning methods

#### **General Motors - Electrification Controls Intern**

6/2017 - 8/2017

- Validated power consumption models for electric vehicles using experimental data
- Developed and troubleshot Simulink models for electrified powertrain energy consumption

## **Apple - Emerging Technologies Intern**

5/2016 - 8/2016

- Developed interactive Matlab tools to analyze and summarize spatial and temporal datasets
- Streamlined a signal simulation pipeline and created GUIs for rapid signal generation
- Summarized work in final presentation, well-received by 20+ cross-functional team members

# University of Michigan Transportation Research Institute - Research Assistant

7/2013 - 8/2015

- Analyzed sensor data using SQL and plotting tool Igor to evaluate active safety performance
- Built Matlab tools to automatically characterize heavy truck suspension behavior from test data

## Teaching

#### Data 8, UC Berkeley - Lead Undergraduate Student Instructor

8/2018 - 12/2018

- Pedagogy lead supervising a team of 4 instructors developing course materials for 1200+ students
- Presented weekly to 40+ instructors regarding course material and educational strategy
- Taught 60+ students weekly in two lab sections applying course material
- Course evaluations consistently above average (personal: 4.6/5, average: 4.3/5)

# Data 8, UC Berkeley - Undergraduate Student Instructor

8/2016 - 5/2018

- Primary lab section instructor teaching computational and inferential thinking with real-world data
- Member of teaching staff responsible for developing course and studying pedagogy

#### **Honors and Awards**

NASA Graduate Fellowship	2021-Present
NSF Graduate Research Fellowship Honorable Mention	2021
Berkeley Engineering Honors to Date - Top 20% GPA	Fall 2015 - Fall 2018
Bronze Medal Winner - Siemens-UC Berkeley Hackathon	2018
Outstanding Graduate Student Instructor Award - Top 9% of GSIs	Spring 2018
Member, Eta Kappa Nu, Mu (Berkeley) Chapter - Top 25% of EECS Majo	ors Fall 2016
College of Engineering Dean's List - Top 10% GPA	Fall 2015, Fall 2016, Spring 2017
Michigan Mathematics Prize Competition - Top 100	2015